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# Adaptive Resonance Theory

ART Networks

Stephen Grossberg &  
Gail Carpenter

# ART Network Varieties

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- Several varieties:
  - ART1: Discrete (e.g. binary) patterns
  - ART2: Continuous patterns ...
  - ARTMAP: supervised learning
  - Fuzzy Art: Fuzzy version of ART1
- All work by competitive learning and a sort of **clustering** (even though not identified as such) + nuances

# Stability-Plasticity Dilemma

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- **stability:** Recognized patterns should be insensitive to noise.
- **plasticity:** System should be capable of learning new patterns.
- The conflict between these is one of the things that ART hopes to resolve.

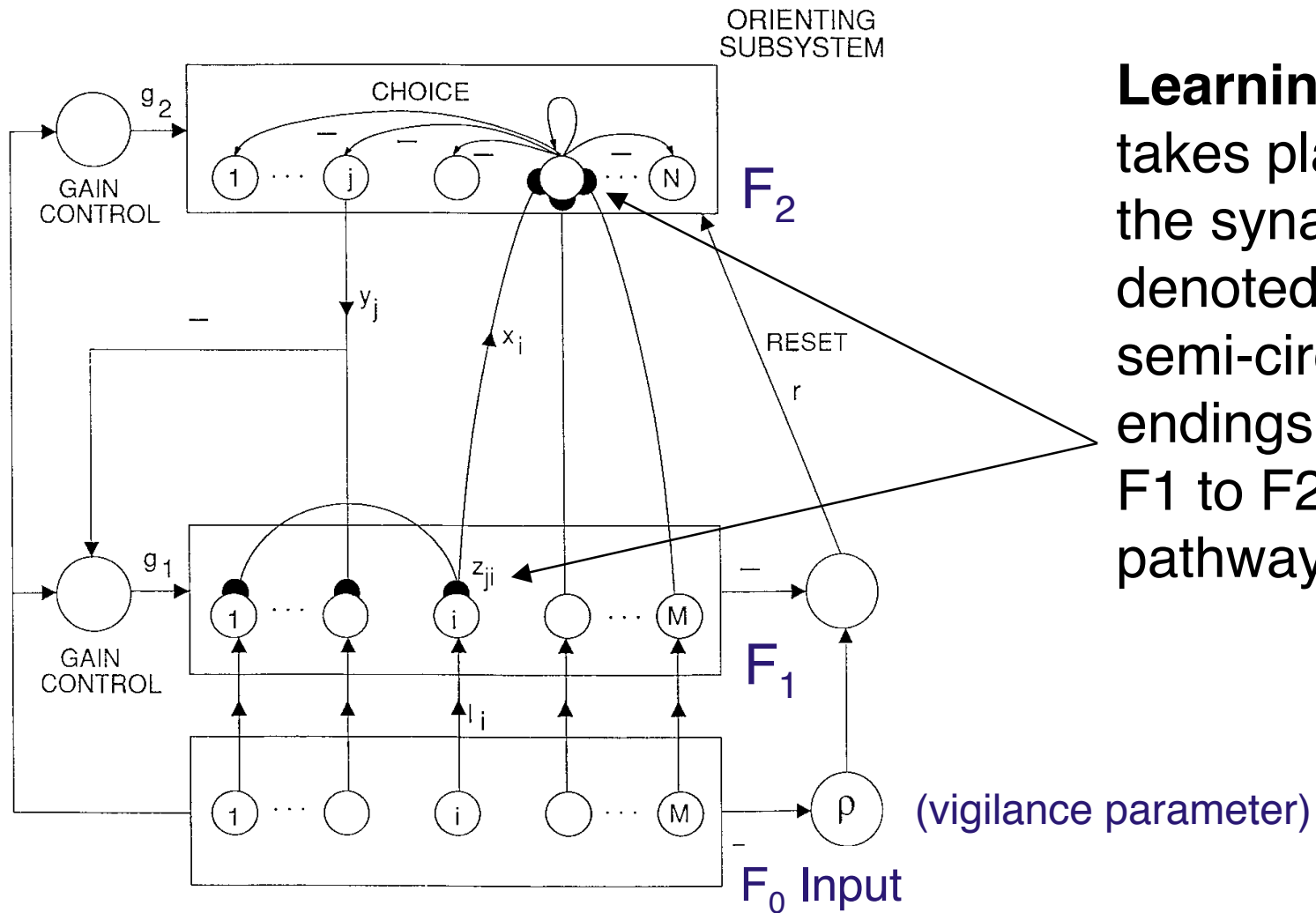
# ART Networks

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- Combine supervised and unsupervised (competitive, clustering)
- Dynamically create new categories
- Biologically motivated by an ODE model
- Models short- and long-term memory

# ART1 Model



**Learning** takes place at the synapses denoted by semi-circular endings in the  $F_1$  to  $F_2$  pathways.

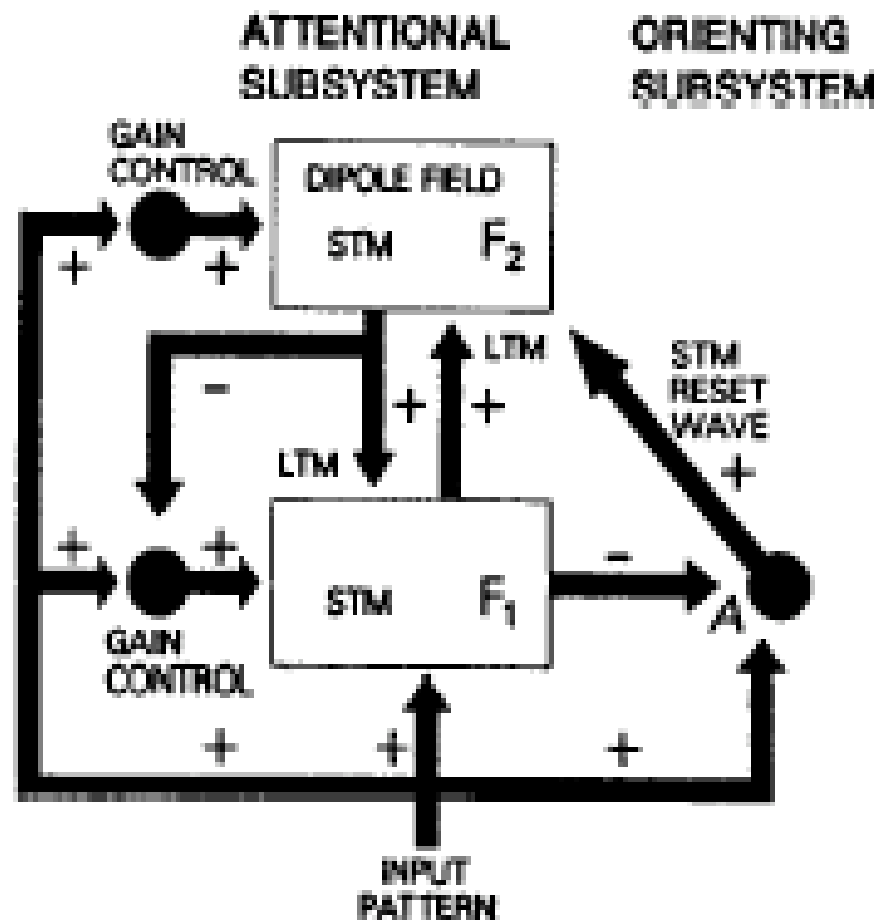
# ART General Workings

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- $F_2$  activities can be interpreted as “making a hypothesis” about input at  $F_1$ .
- The LTM-gated signals from all the active  $F_2$  nodes are added to generate the total top-down feedback pattern from  $F_2$  to  $F_1$ . This pattern plays the role of a **learned expectation**. Activation of this expectation “tests the hypothesis” of the active  $F_2$  category.
- The expected prototype of the category are compared with the bottom-up input pattern (exemplar) to  $F_1$ .

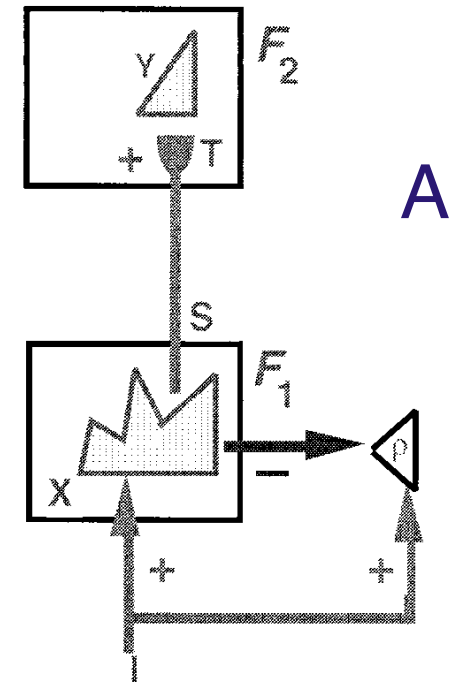
# Diagram from Carpenter and Grossberg, 1988



# ART search for a recognition code (A of 4)

[Grossberg and Merrill (1996)]

- The input pattern  $I$  is instated across the feature detectors at level  $F_1$  as a short-term memory (STM) activity pattern  $X$ .
- Input  $I$  also nonspecifically activates the orienting subsystem  $A$ . STM pattern  $X$  is represented by the hatched pattern across  $F_1$ .
- Pattern  $X$  both inhibits  $A$  and generates the output pattern  $S$ .
- Pattern  $S$  is multiplied by long term memory (LTM) traces and added at  $F_2$  nodes to form the input pattern  $T$ , which activates the STM pattern  $Y$  across the recognition categories coded at level  $F_2$ .

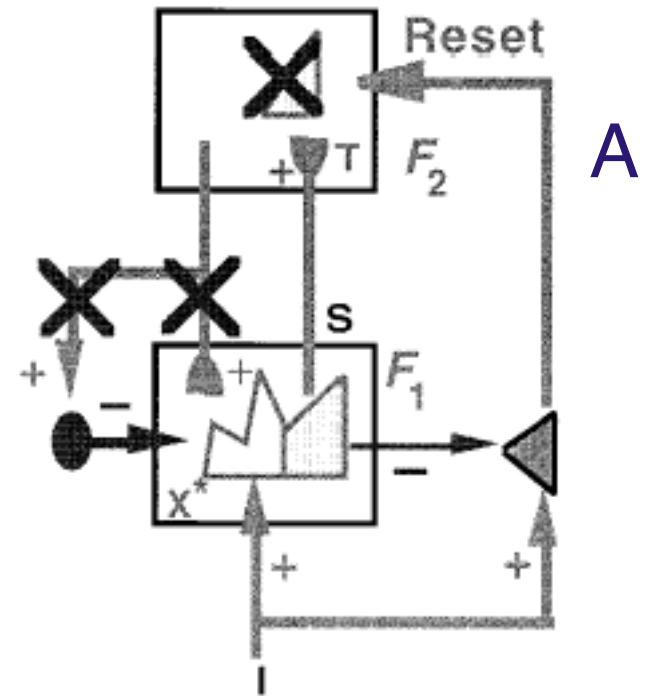






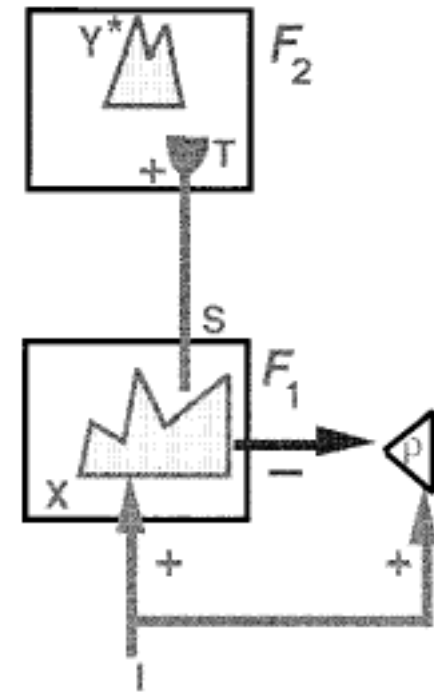
## ART search for a recognition code (C of 4)

- If inhibition decreases sufficiently [vigilance condition not met], A releases at a nonspecific arousal wave to  $F_2$ , which resets the STM pattern Y at  $F_2$ .



## ART search for a recognition code (D of 4)

- After Y is inhibited, its top-down prototype signal is eliminated, and X can be reinstated at  $F_1$ .
- Enduring traces of the prior reset lead X to activate a different STM pattern  $Y^*$  at  $F_2$ .
- If the top-down prototype due to  $Y^*$  also mismatches I at  $F_1$ , then the search for an appropriate  $F_2$  code continues *until a more appropriate*  $F_2$  representation is selected. Then an attentive resonance develops and learning of the attended data is initiated.



# Hypothesis Testing

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- In an ART model, learning does not occur as soon as some winning  $F_2$  activities are stored in STM. Instead,  $F_2$  activities can be interpreted as “making a hypothesis” about input at  $F_1$ .
- The LTM-gated signals from all the active  $F_2$  nodes are added to generate the total top-down feedback pattern from  $F_2$  to  $F_1$ . This pattern plays the role of a learned expectation. Activation of this expectation “tests the hypothesis” of the active  $F_2$  category.
- The expected prototype of the category are compared with the bottom-up input pattern (exemplar) to  $F_1$ .

# ART Learning

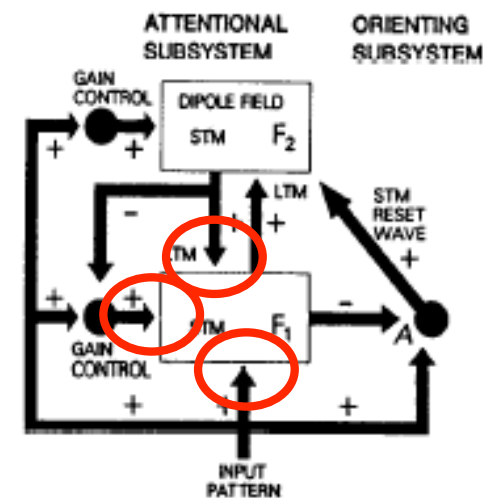
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- The resonant state, rather than bottom-up activation, drives the learning process (thus “adaptive resonance” theory):
  - “resonance” = mutual reinforcement between input and storage layers
  - “adaptive” = weights are adjusted when resonance occurs
- ART systems learn prototypes rather than exemplars because the attendant feature vector  $\mathbf{X}^*$  rather than the input exemplar itself is learned.

# 2 of 3 Rule

- The ART attentive matching process is realized by combining bottom-up inputs and top-down expectations with a nonspecific arousal process that is called attentional gain control – an  $F_1$  node can be fully activated only if **two of the three input sources** that converge on the node send positive signals to the node at a given time – thus the constraint is called the “2/3 rule”.
- It is the 2/3 rule that enables an ART network to solve the stability-plasticity dilemma.



# ART1 Viewpoints

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- Two kinds of explanations:
  - neural - as just seen
  - algorithmic
- The first is more complicated, since it involves neural explanations for the control aspects of the algorithmic approach.

# Basic ART *Algorithm*

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- Input pattern presented to input layer.
- Storage layer indicates tentative hypothetical classification.
- Input layer decides if hypothetical is **close enough**; if so, done.
- If not, storage layer indicates alternate hypothesis.
- The above two steps are repeated until the hypothetical classification is accepted.
- *All* hypotheses could be rejected; in this case, a **new** class is created in the storage layer.



# ART1 (Discrete Patterns)

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- training pattern  $x \in \{0, 1\}^n$
- prototype patterns  $w_j \in \{0, 1\}^n$
- Storage unit computes  
 $y_j = w_j x / \|w_j\|^2$  for each prototype
- The winner is the prototype with the largest  $y_j$
- For **acceptance** it is **necessary** that,  $y_j > \|x\|^2 / n$ , where  $n$  is the number of dimensions.
- This means that sufficiently-many bits must **match**.

# ART1

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- Assuming that the acceptance test is passed, it is also required that the **vigilance test** also be:

$$w_j \cdot x / \|x\|^2 > \rho$$

where  $\rho$  is an adjustable parameter called **vigilance**.

This means that the input and the pattern share a sufficient fraction of 1's.

# ART1

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- If the acceptance test is passed, but the vigilance test is not:
  - the prototype in question is temporarily omitted from consideration;
  - a new competition takes place
- until a prototype is found for which both tests are passed.
- If no prototype is found, a new class  $k$  is created with

$$w_k = x$$

# ART1

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- The **higher** the **vigilance**, the more likely a new pattern is to be introduced.
- Lower vigilance will allow one input to pass as another pattern.

# ART1 Issues

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- Subset-Superset dilemma:
  - If one pattern is **contained in** another, then a given input may have the same inner product with two different prototypes.
  - Can be resolved by allowing weights other than  $\{0, 1\}$  and **normalizing** the prototypes.

# ART1 Command-Line Demo

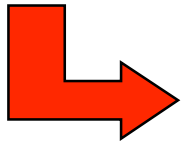
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- `/cs/cs152/art1/`
- `art1 < letters.50.in`
- Number is % vigilance coded in file.

# Matlab ART1 Demo

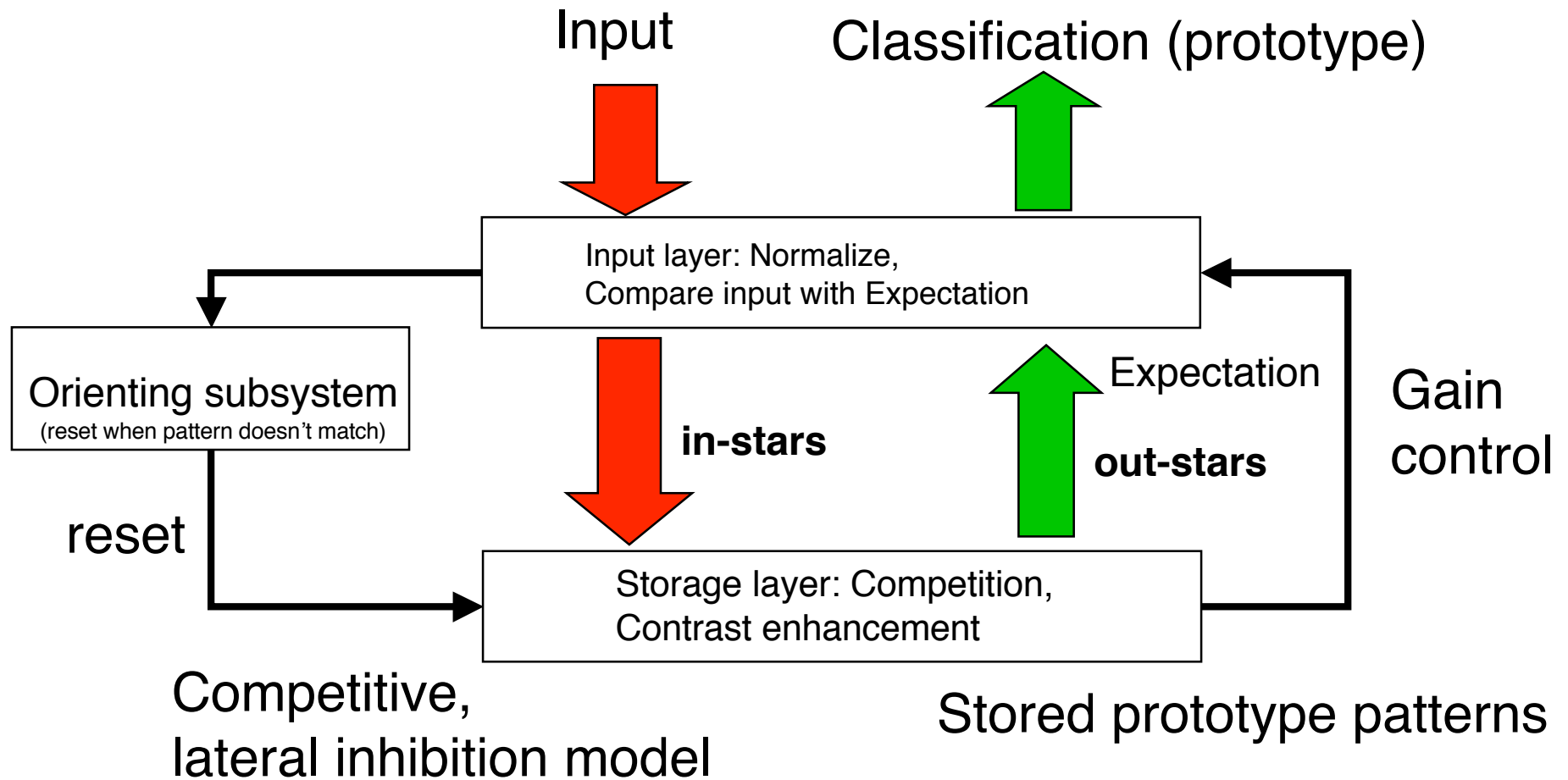
Increasing **vigilance** causes the network to be more selective, to introduce a new prototype when the fit is not good.



The screenshot shows a window titled 'nnd16a1' with a menu bar (File, Edit, Tools, Window, Help). The main area is divided into 'Neural Network DESIGN' and 'ART1 Algorithm'. Under 'Neural Network DESIGN', there are four 5x5 grids labeled 'Pattern 1' through 'Pattern 4'. Pattern 1 and 3 are green, Pattern 2 is yellow, and Pattern 4 is yellow with a blue border. Below each grid is a 'Present' button. Under 'ART1 Algorithm', there are four 5x5 grids labeled 'Prototype 1' through 'Prototype 4'. Prototype 1 is yellow, Prototype 2 is yellow with red cells, Prototype 3 is yellow with red cells, and Prototype 4 is red. To the right of the grids is a text box with instructions: 'Click on the green grids to define patterns. Click on the buttons to present them. The ART1 network's prototype patterns are shown below. Use the slider bar to set the ART1 vigilance.' Below the text box are 'Clear', 'Contents', and 'Close' buttons. At the bottom, there is a 'Vigilance (rho):' slider bar ranging from 0.0 to 1.0, with the current value set to 0.6. A small icon of a brain with '010' is in the top right corner. The text 'Chapter 16' is at the bottom right.

Try different patterns

# ART: instars and outstars

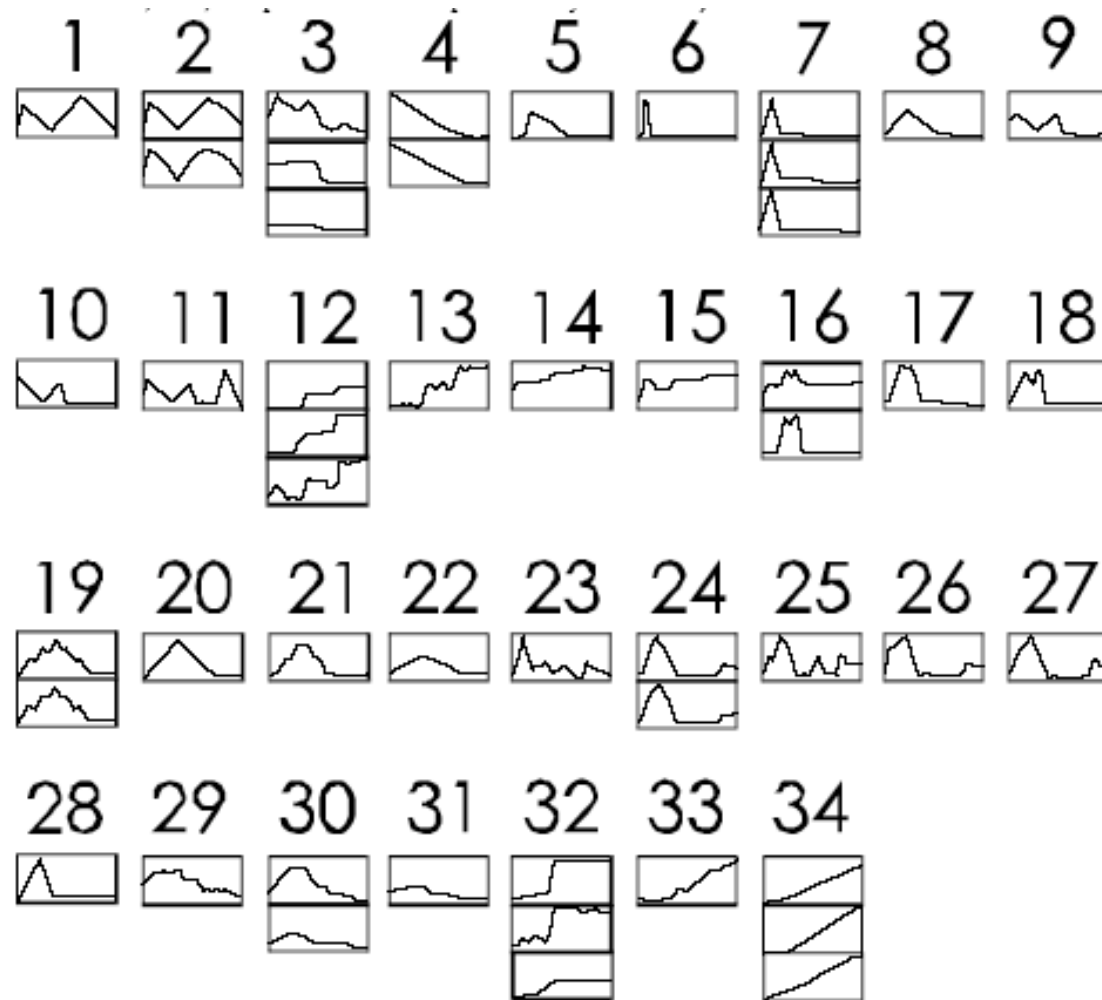




# ART2 Clustering (higher vigilance)

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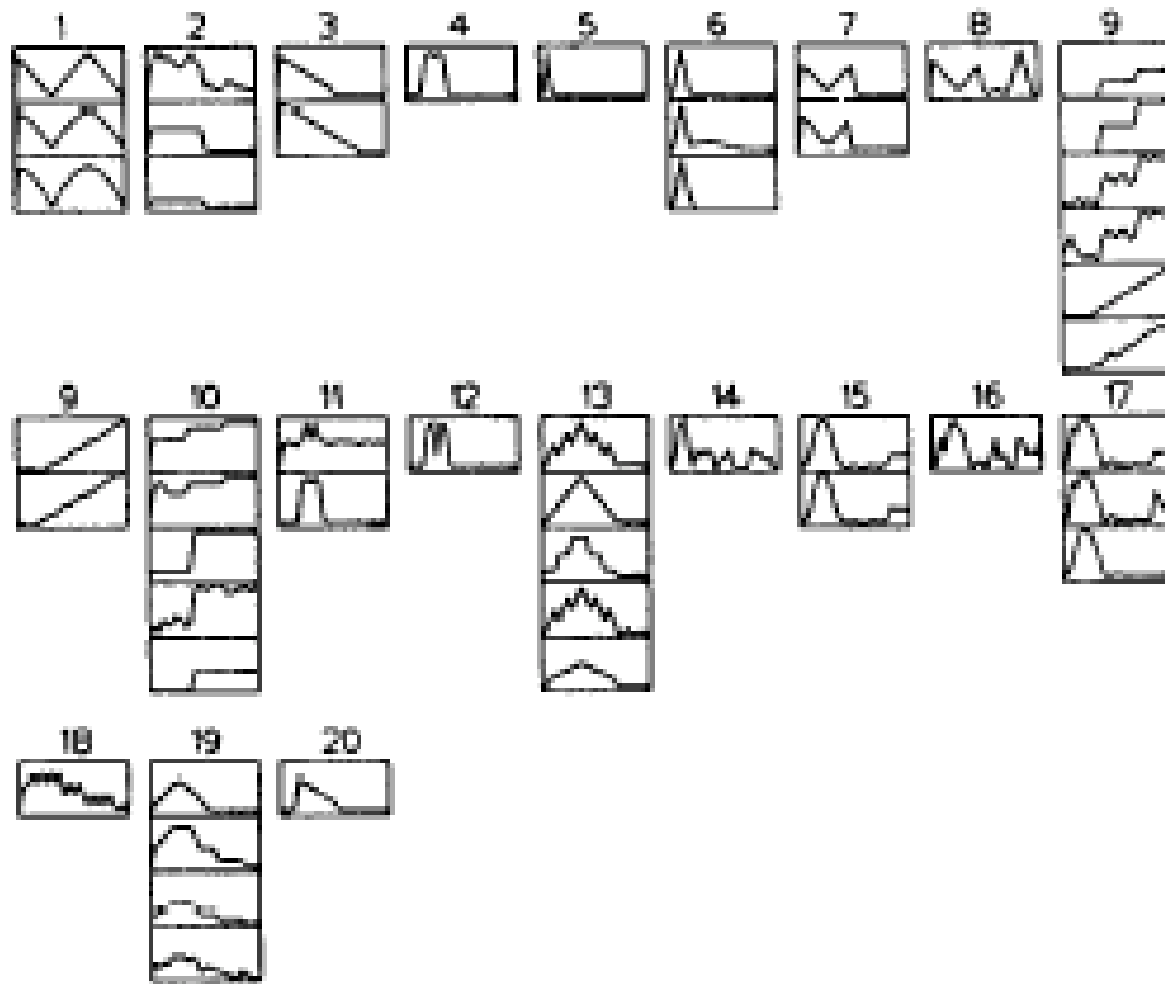
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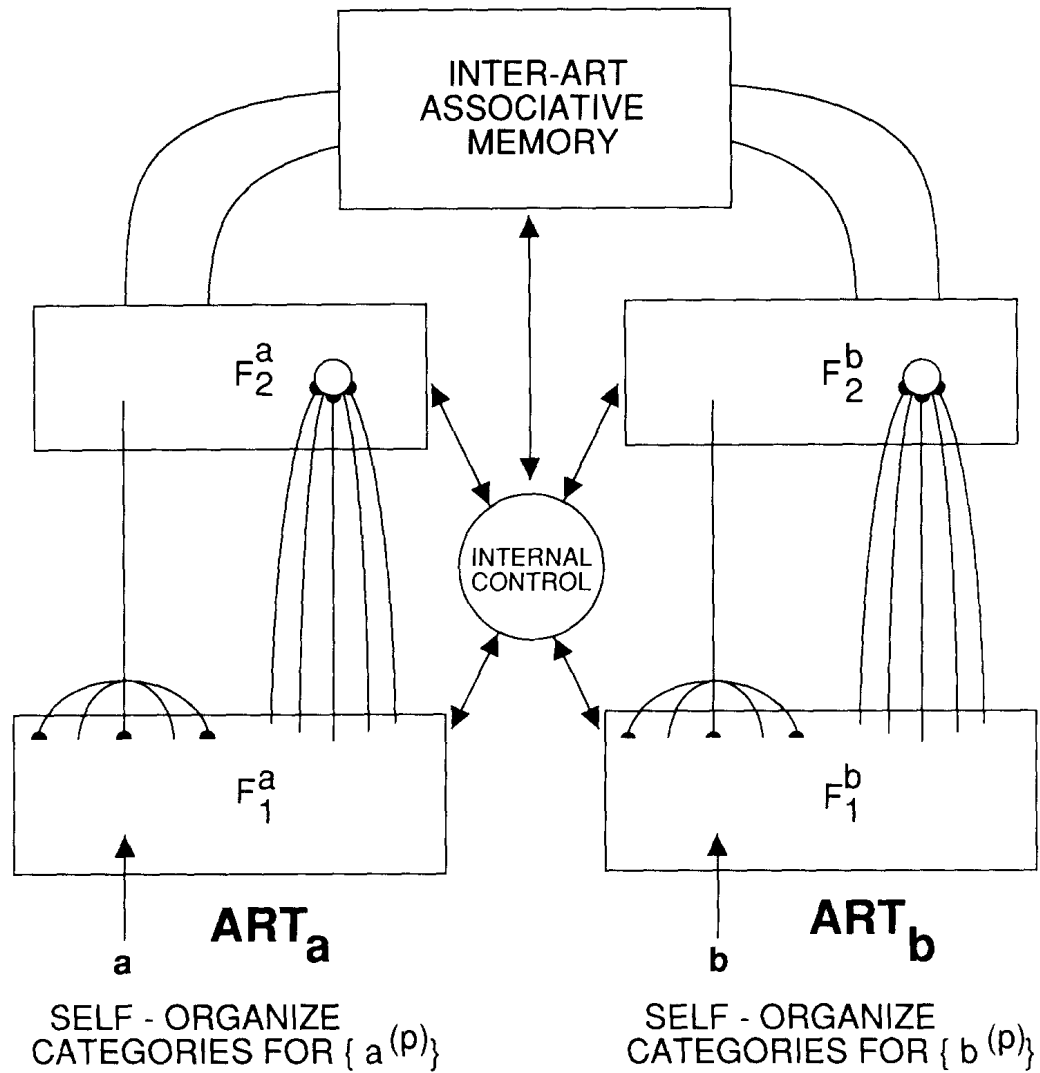
# ART2 Clustering (lower vigilance)

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# ART Map



# ART Map vs. BackProp

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	Predictive ART	Back Propagation
supervised	yes	yes
self-organizing	yes	no
real-time	yes	no
self-stabilizing	yes	no
learning:	fast or slow match	slow mismatch

# Some ART Applications

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- Disease identification (HMC Math Clinic)
- Tech support email automation (text similarity) (HMC CS Clinic)
- Satellite data anomaly detection (HMC CS Clinic)
- Music recognition
- Distinguishing poisonous vs. edible mushrooms
- Modeling biological neural processes